

**ANALYSIS OF THE LAWS OF COTTON BLEND MOVEMENT IN
THE RUBBER PLANK SEPARATION DRUM OF THE COTTON
REGENERATOR**

**АНАЛИЗ ЗАКОНОМЕРНОСТЕЙ ДВИЖЕНИЯ ХЛОПКОВОЙ
СМЕСИ В БАРАБАНЕ ДЛЯ РАЗДЕЛЕНИЯ РЕЗИНОВЫХ ДОСОК
РЕГЕНЕРАТОРА ХЛОПКА**

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Abstract

In the article, a system of equations describing the movement of cotton on the surface of an improved rubber-plate drum for separating cotton pieces from the cleaning saws of the cotton regenerator was developed, and graphs of the dependence of the rubber-plate deviation angle and the cotton piece mass on the time of transportation of cotton pieces in the rubber-plate drum were made according to the numerical solution of the problem.

Key words: Regenerator, plank, rubber, separation, effect, drum.

Абстрактный

В статье разработана система уравнений, описывающая движение хлопка по поверхности усовершенствованного резино-пластинчатого барабана для отделения кусочков хлопка от чистящих пил регенератора хлопка, и графики зависимости угла отклонения резино-пластинчатого барабана и массы кусочка хлопка от времени транспортировки из кусочков хлопка в барабане с резиновыми пластинами были изготовлены в соответствии с численным решением задачи.

Ключевые слова: регенератор, планка, резина, сепарация, эффект, барабан.

In the recommended cotton regenerator, the fiber seeds caught by the drum teeth are pulled out by a rubber-plate drum and moved along the axis and transported to the exit zone. In this case, the rubber plates are located perpendicular to the axis of the drum. As a result, a large piece of cotton creates an additional

force moving along the axis. Therefore, it is important to theoretically analyze the movement of the fibrous seed on the surface of the planks. To solve the problem, a calculation scheme was built in which the forces acting on the piece of cotton were applied [1, 2]. This calculation scheme is presented in Figure 1.

The forces affecting the calculation scheme are as follows: \bar{G} -gravity force vector; $\bar{F}_{\text{МК}}$ -centrifugal force vector; \bar{F}_x - air resistance force vector; $\bar{F}_{\text{кор}}$ - coriolis force vector; $\bar{F}_{\text{иш}}$ -friction force vector; \bar{N} -reaction force vector.

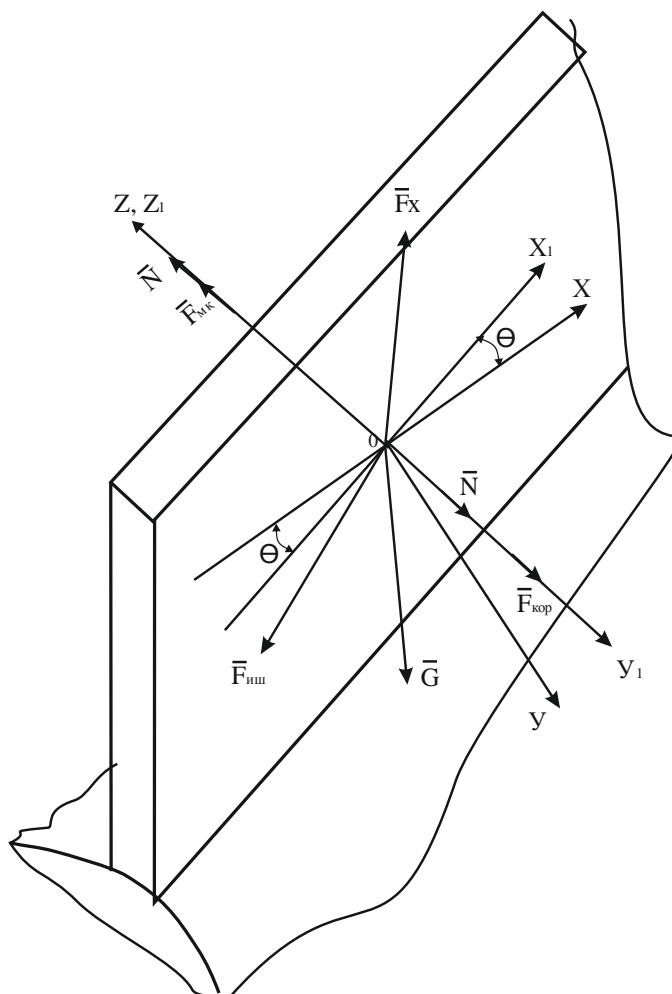


Figure 1. Calculation scheme representing the movement of a piece of cotton on the surface of a rubber sheet.

Taking these forces and the projection of the inertial force on the coordinate axes X, U, Z, we create the equilibrium condition based on the D'Alambert principle [3, 4]:

$$\sum_{i=1}^n F_{ix} = 0; \quad \sum_{i=1}^n F_{iy} = 0; \quad \sum_{i=1}^n F_{iz} = 0 \quad (1)$$

We take the projections of all forces and form a system of differential equations representing the law of motion of a piece of cotton on the surface of a rubber plate:

$$\begin{aligned} m_n \ddot{x} &= -kV_x^2 \cos\beta_1 - N \cos\beta_2 - F_{\text{коп}} \cos\beta_3 - F_{\text{инт}} \cos\beta_4; \\ m_n \ddot{y} &= -kV_x^2 \sin\beta_1 + N \sin\beta_2 + F_{\text{коп}} \sin\beta_3; \\ m_n \ddot{z} &= -G - F_{\text{инт}} \sin\beta_4 + F_{\text{МК}}. \end{aligned} \quad (2)$$

where $\beta_1, \beta_2, \beta_3, \beta_4$ are the angles formed by the corresponding forces with the X coordinate axis.

Accordingly, we form the acting forces as follows.

$$\begin{aligned} m_n \ddot{x} &= -kV_x^2 \cos\beta_1 - N \cos\beta_2 - 2m_n \dot{x} \omega_b \cos\Theta; \\ m_n \ddot{y} &= -kV_x^2 \sin\beta_1 + N \sin\beta_2 + 2m_n \dot{x} \omega_b \cos\Theta; \\ m_n \ddot{z} &= -m_n g - N f \sin\beta_4 + m_n \omega_b^2 (R_b + h/2 + Z). \end{aligned} \quad (3)$$

The parameters of the numerical solution of the problem were implemented in the initial calculation values:

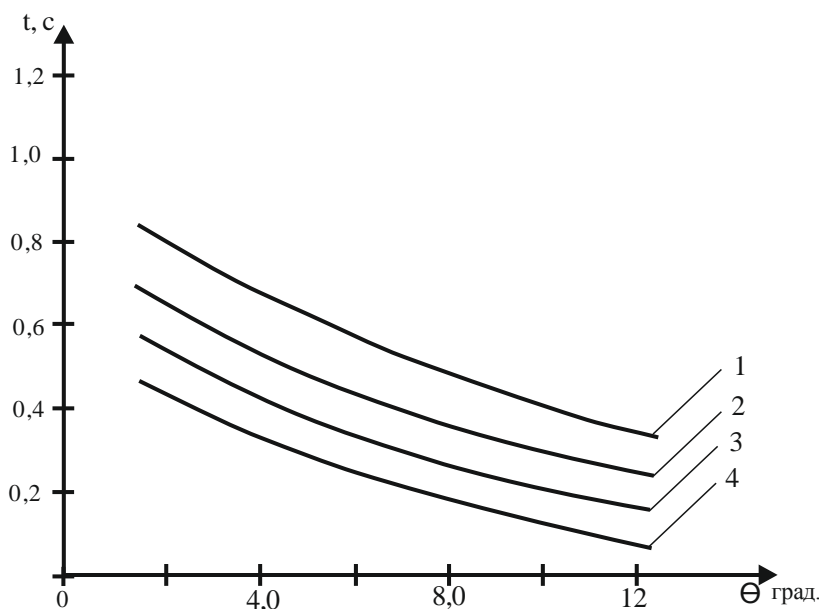
$$\begin{aligned} m_n &= (0,2-2,0) \cdot 10^{-3} \text{ kg}; \quad f = (0,25-0,3); \quad g = 9,81 \text{ m/c}^2; \quad \Theta = 5^0-10^0; \quad \omega_b = (95-110) \text{ c}^{-1}; \\ l &= 1,9 \cdot 10^3 \text{ m}; \quad V_x = (2,0-3,0) \text{ m/c}; \quad k = 1,5-2,5; \quad \beta_1 = 30^0-45^0; \quad \beta_2 = 25^0-60^0; \quad \beta_3 = 30^0-50^0; \\ \beta_4 &= 15^0-35^0. \end{aligned}$$

In the recommended cotton regenerator, the dimensions of the drum that separates the cotton pieces from the teeth should be selected in such a way that it first completely removes the cotton pieces from between the teeth, secondly, it is necessary to transfer them to the transportation zone faster, and thirdly, it is necessary not to damage the cotton fibers as much as possible. In this case, after the fiber seed is removed from the saw tooth several times, the rubber-plates are affected along the axis and ejected. These repetitions, depending on the mass of the cotton piece, are transported up to (3-7) times on the surface of the rubber plate to the moving zone. Therefore, it is important to determine the time to remove the cotton piece from the drum with rubber plate.

In this case, the transportation time was assumed to be at a distance equal to (0.6-0.7) l m of the average drum. Because not all cotton pieces move along the full length of the drum. Also, by determining the speed of movement along the X

axis, then the time of transportation is found. In this case, the numerical solution of the system of differential equations (2) was carried out on a computer. The time of transportation of a piece of cotton is determined by the equation (3):

$$t = \frac{X}{\dot{X}} \quad (3)$$



1- $m_n=2,0 \cdot 10^{-3}$ кг; 2- $m_n=1,5 \cdot 10^{-3}$ кг; 3- $m_n=1,0 \cdot 10^{-3}$ кг; 4- $m_n=0,5 \cdot 10^{-3}$ кг.

Figure 2. Graphs of the dependence of the time of transportation of cotton pieces in a rubber-plate drum on the angle of deviation of rubber-plates and the mass of the cotton piece.

Figure 2. shows graphs of the dependence of the time of transportation of cotton pieces in a rubber-plate drum on the angle of deviation of rubber-plates and the mass of the cotton piece. Based on the analysis of the obtained studies, it can be seen that when the angle of deviation of the rubber plates increases from 50 to 150, the transportation time of fiber seed with $m_n=0.5 \cdot 10^{-3}$ kg decreases from 0.42 s to 0.097 s in nonlinear connection. Accordingly, when the mass of a piece of cotton is $2.0 \cdot 10^{-3}$ kg, its transportation time decreases from 1.0 s to 0.39 s in nonlinear mode.

Conclusion

Therefore, for faster transportation of cotton pieces of different mass, it is recommended to make the deviation angle of the rubber plates $\Theta=7^0$.

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